

FLUX

BASED ON LECTURE NOTES BY JAMES MCKERNAN

Let $M \subset \mathbb{R}^3$ be a two dimensional parametrized surface defined by a diffeomorphism $\vec{r}: D \rightarrow M$, for some $D \subset \mathbb{R}^2$.

Definition 1. Let $f: M \rightarrow \mathbb{R}$ be a scalar function on M . The integral of f over M is defined as

$$\iint_M f \, dS = \iint_D f(\vec{r}(s, t)) \left\| \frac{\partial \vec{r}}{\partial s}(s, t) \times \frac{\partial \vec{r}}{\partial t}(s, t) \right\| \, ds \, dt.$$

We also denote sometimes $\vec{T}_t = \partial \vec{r} / \partial t$ and likewise $\vec{T}_s = \partial \vec{r} / \partial s$.

If we define $\vec{r}(s, t) = (x(s, t), y(s, t), z(s, t))$, then

$$\iint_M f \, dS = \iint_D f(\vec{r}(s, t)) \sqrt{\left| \frac{\partial(x, y)}{\partial(s, t)} \right|^2 + \left| \frac{\partial(y, z)}{\partial(s, t)} \right|^2 + \left| \frac{\partial(x, z)}{\partial(s, t)} \right|^2} \, ds \, dt.$$

Example 2. Suppose M is the graph of a function $g: D \rightarrow \mathbb{R}$. Then M is parametrized by $\vec{r}(s, t) = (s, t, g(s, t))$. Hence

$$\frac{\partial(x, y, z)}{\partial(s, t)} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \\ g_x & g_y \end{pmatrix}$$

and

$$\begin{aligned} \frac{\partial(x, y)}{\partial(s, t)} &= \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \\ \frac{\partial(y, z)}{\partial(s, t)} &= \begin{pmatrix} 0 & 1 \\ g_x & g_y \end{pmatrix} \\ \frac{\partial(x, z)}{\partial(s, t)} &= \begin{pmatrix} 1 & 0 \\ g_x & g_y \end{pmatrix}. \end{aligned}$$

Therefore

$$\iint_M f \, dS = \iint_D f(s, t, g(s, t)) \sqrt{1 + g_x(s, t)^2 + g_y(s, t)^2} \, ds \, dt.$$

Example 3. The area of a paraboloid $g(x, y) = x^2 + y^2$ over $D = \{(s, t) \in \mathbb{R}^2 : s^2 + t^2 \leq 1\}$ is

$$\begin{aligned} \iint_D \sqrt{1 + 4s^2 + 4t^2} \, ds \, dt &= \int_0^{2\pi} \int_0^1 \sqrt{1 + 4r^2} r \, dr \, d\theta \\ &= 2\pi \int_0^1 \frac{1}{2} \sqrt{1 + 4u} \, du \\ &= \frac{\pi}{6} (5^{3/2} - 1). \end{aligned}$$

Definition 4. Let $\vec{F}: M \rightarrow \mathbb{R}^3$ be a vector field on M . The flux of \vec{F} through M is defined by

$$\iint_M \vec{F} \cdot d\vec{S} = \iint_D \vec{F}(\vec{r}(s, t)) \cdot \left(\frac{\partial \vec{r}}{\partial s} \times \frac{\partial \vec{r}}{\partial t} \right) \, ds \, dt.$$

Let

$$\hat{n} = \frac{\frac{\partial \vec{r}}{\partial s} \times \frac{\partial \vec{r}}{\partial t}}{\left\| \frac{\partial \vec{r}}{\partial s} \times \frac{\partial \vec{r}}{\partial t} \right\|}.$$

Then

$$\iint_M \vec{F} \cdot d\vec{S} = \iint_M (\vec{F} \cdot \hat{n}) dS.$$

Note: because \vec{r} is a diffeomorphism, it always points to the “same side” of M .

Example 5. Find the flux of the vector field given by

$$\vec{F}(x, y, z) = x\hat{i} + 2y\hat{j} + 3z\hat{k},$$

through the triangle M given by

$$M = \{(x, y, z) \in \mathbb{R}^3 : x \geq 0, y \geq 0, z \geq 0, x + y + z = 1\}.$$

The parametrization is $\vec{r} = (x, y, z) = (s, t, 1 - s - t)$, for

$$D = \{(s, t) : 0 \leq s \leq 1, 0 \leq t \leq 1 - s\}.$$

Hence

$$\vec{T}_s \times \vec{T}_t = \begin{pmatrix} \hat{i} & \hat{j} & \hat{k} \\ 1 & 0 & -1 \\ 0 & 1 & -1 \end{pmatrix} = \hat{i} + \hat{j} + \hat{k}$$

and

$$\vec{F}(\vec{r}(s, t)) \cdot (\vec{T}_t(s, t) \times \vec{T}_s(s, t)) = x + 2y + 3z = 3 - 2s - t.$$

Therefore the flux is

$$\begin{aligned} \iint_D (3 - 2s - t) ds dt &= \int_0^1 \int_0^{1-t} (3 - 2s - t) ds dt \\ &= 1. \end{aligned}$$

Example 6. Recall that the sphere can be parametrized by

$$\vec{r}(\phi, \theta) = (a \sin \phi \cos \theta, a \sin \phi \sin \theta, a \cos \phi).$$

Hence the tangent vectors are

$$\begin{aligned} \vec{T}_\phi &= \frac{\partial \vec{r}}{\partial \phi} = (a \cos \phi \cos \theta, a \cos \phi \sin \theta, -a \sin \phi), \\ \vec{T}_\theta &= \frac{\partial \vec{r}}{\partial \theta} = (-a \sin \phi \sin \theta, a \sin \phi \cos \theta, 0). \end{aligned}$$

and

$$\begin{aligned} \vec{T}_\phi \times \vec{T}_\theta &= a^2 \sin^2 \phi \cos \theta \hat{i} + a^2 \sin^2 \phi \sin \theta \hat{j} + a^2 \cos \phi \sin \phi \hat{k} \\ &= a \sin \phi \cdot \vec{r}(\phi, \theta). \end{aligned}$$

Let $\vec{F}(x, y, z)$ be constant: $\vec{F} = (F_1, F_2, F_3)$. Calculate the flux of \vec{F} through the sphere.

The flux is

$$\begin{aligned}\iint_M \vec{F} \cdot \vec{T}_\phi \times \vec{T}_\theta \, dS &= \int_0^\pi \int_0^{2\pi} \vec{F} \cdot \vec{T}_\phi \times \vec{T}_\theta \, d\theta \, d\phi \\ &= \int_0^\pi a \sin \phi \int_0^{2\pi} \vec{F} \cdot \vec{r}'(\phi, \theta) \, d\theta \, d\phi \\ &= a \int_0^\pi \sin \phi \int_0^{2\pi} (F_1 a \sin \phi \cos \theta + F_2 a \sin \phi \sin \theta + F_3 a \cos \phi) \, d\theta \, d\phi \\ &= 2\pi a^2 F_3 \int_0^\pi \sin \phi \cos \phi \, d\phi \\ &= 0.\end{aligned}$$